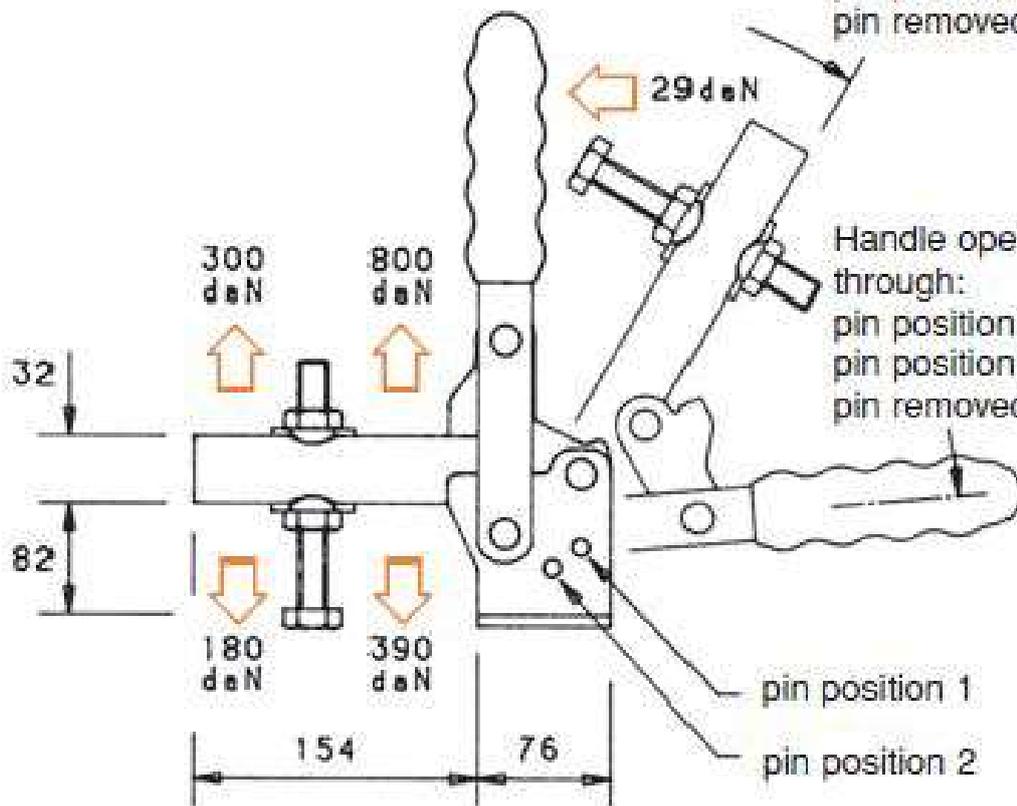
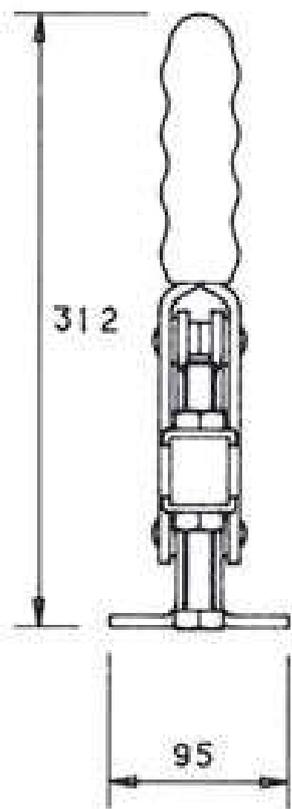


Arm opens through:
 pin position 1 = 90°
 pin position 2 = 120°
 pin removed = 180°



Handle opens through:
 pin position 1 = 65°
 pin position 2 = 80°
 pin removed = 110°

pin position 1
 pin position 2